



# A JPL Planetary Science Summer School Trojan and Centaur Reconnaissance Mission: Mission Design

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### TRACER (Trojan And Centaur Reconnaissance) Mission Overview

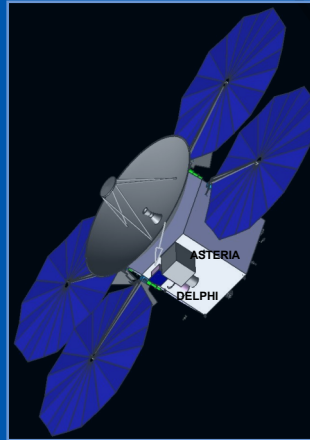
TRACER would be the first spacecraft to visit a Trojan and a Centaur. The mission's scientific objectives are to determine if Trojans and Centaurs formed in their present positions, test dynamical models for the evolution of the solar system, and place Trojans and Centaurs in context with other small outer solar system bodies.

TRACER would leave Earth on an Atlas V 541 around March 12, 2019. The spacecraft utilizes a Solar Electric Propulsion (SEP) system. The trajectory includes the flybys of the Trojan Antenor on November 28, 2023 and the Centaur 2001 BL41 on February 7, 2027. Each flyby includes high resolution imaging, visible and infrared spectral mapping, and chemical and physical characterization. The spacecraft would also perform dust flux measurements in the Trojan asteroid region and a photopolarimetric survey of the Trojan asteroid region.

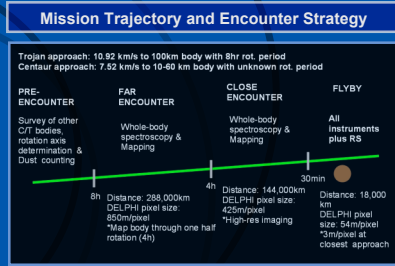
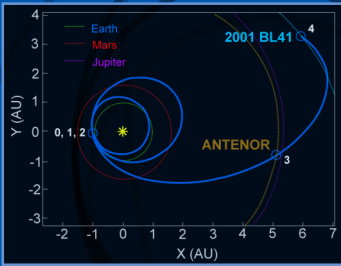
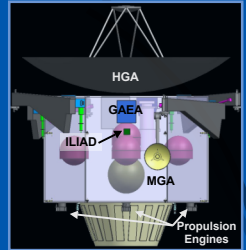
This is a New Frontiers class mission with a total PI-managed mission cost of \$650M (FY2009\$). The use of a medium range launch vehicle increases this cap to \$690M. This pre-Phase A design has a cost of \$716M, including JPL's standard 30% reserve, which is \$26M over the cap.

The following mission design was developed during the 2009 JPL Planetary Science Summer School by a group of graduate students and recent PhDs in a variety of science and engineering fields working in conjunction with Team X at JPL.

This design is a response to the 2009 New Frontiers Announcement of Opportunity.



- #### Spacecraft Overview
- Atlas V 541 launch vehicle
  - Dual cold redundant
  - No radioisotopes
  - Hexagonal bus
  - Communication
    - 4 m HGA
    - 0.75 m MGA
  - Solar Power
    - 4 ultra-flex arrays
  - Propulsion
    - Solar Electric (Xenon)
    - Chemical (Hydrazine)
  - 4 Instruments
    - ASTERIA
    - DELPHI
    - GAEA
    - ILIAD
    - radio science



### Spacecraft Subsystems

- #### Design Assumptions
- GAEA and ILIAD mounted in direction of travel
  - ASTERIA and DELPHI co-pointed
  - 600 μrad control, 30 μrad/sec stability

- #### Power
- 4 MultiFlex solar panels
    - Triple junction solar cells, cell packing factor = 0.89, 58.8 m<sup>2</sup> surface area
  - 5 30W-hr Li-Ion batteries
    - 4 primary, 1 redundant
  - Power output:
    - 19.8 kW at 1 AU
    - 540 W at end of mission

- #### Propulsion
- Main Engine: Solar Electric Propulsion
    - 4 BPT-4000 developed by Aerojet
    - Propellant: 1807 kg of Xe in 5 tanks
    - Nominal operational power 4.5 kW/engine
  - RCS Chemical Monopropellant
    - 16 Aerojet MR-103M (1N each)
    - Isp between 221 and 206 seconds
    - Propellant: 41 kg of Hydrazine

- #### Command and Data Handling/Software
- Flight Computer: 133Mhz PowerPC FSW:MSAP based, NPR compatible
  - Data storage: 96GB in-chassis NVRAM card (heritage: WISE mission)
  - High-speed LVDS interface: Telecom, DELPHI, and ILIAD
  - Low-speed 1553 bus interface: ACS, ASTERIA, and GAEA

- ### Science Objectives and Instrumentation
- Determine the formation region of the Trojans and Centaurs
  - Determine the physical properties (size, mass, density) of a Trojan and a Centaur
  - Measure dust fluxes in the outer solar system
  - Determine the chemical composition of Trojan and Centaur volatiles, ices and organics
  - Map the color, albedo and surface morphology of a Trojan and Centaur at high resolution

Instrument	Description	Heritage	Mass	Power
ASTERIA	Visible and near infrared spectrometer	Europa Orbiter	28 kg	25 W
	• Images at 3 mrad/pixel, two 640 x 480 HgCdTe detectors			
DELPHI	Narrow angle camera	Hayabusa AMICA New Horizons LORRI	25 kg	10 W avg 2 W sleep
	• CCD Camera: 2048 by 2048 pixels, 10 μm/pixel			
	• Nominal Field of view (FOV): 6 mrad, IFOV: 3 μrad			
GAEA	Ion and neutral mass spectrometer	Cassini INMS	10 kg	23 W avg 13 W sleep
	• 1-100 amu range, M/ΔM ≥ 100			
ILIAD	Dust counter	New Horizons VBSDC	1.6 kg	5 W
	• 0.1 m <sup>2</sup> collector			

### TRACER Spacecraft

- #### Attitude Control System
- 3-axis stabilized, fine-pointing using reaction wheels with monoprop thrusters for coarse pointing and momentum dumping
  - Stellar and inertial attitude determination using precision star trackers and gyros
  - Full onboard redundancy
  - System Design Drivers:
    - Wheel torque: flyby maneuver (0.55°/sec)
    - Wheel momentum: slewing (90° in 5min)
    - Pointing Knowledge: Delphi (15 arcsec)
    - Pointing Control: Delphi (120 arcsec)
    - Pointing Stability: Delphi (6 arcsec/sec)

- #### Telecom and Ground Systems
- X-band, SSPA – 5W RF, 15W DC
  - Antennas:
    - HGA: fixed (ACS pointing), 75 kg, pointing accuracy = 0.04°
    - MGA: gimballed (encounter Doppler tracking and emergency communication)
    - 2x LGA antennas (launch)
  - Redundant design, NEAR-Shoemaker heritage
  - Links:
    - Carrier-only link for Doppler tracking
    - Data volume: 18 Gb at Trojan, 11 Gb at Centaur includes over head. Additional data during pre-encounter, cruise phase (minor)
  - DSN 34 m Beam WaveGuide (BWG) subnet
    - Trojan downlink @ 6 kbps, 8-hr pass/day for 105 days
    - Centaur downlink @ 3 kbps, 8-hr pass/day for 125 days

- #### Thermal
- The shortwave detector on ASTERIA is passively cooled to 160 K and the longwave detector is cooled to 80 K by a radiator
  - The spacecraft and Sun are excluded from the field of view
  - The SEP tanks are kept at 25 °C
  - The PPU for the SEP tanks requires a thermal radiator

### Cost

Development Cost	CBE	Res.	PBE
Phase A	\$12.3 M	30%	\$15.9 M
Phase B	\$43.7 M	30%	\$59.9 M
Phase C/D	\$372.4 M	30%	\$483.6 M
Operations Cost	\$142.0 M	12%	\$159.6 M
Project Cost (w/o LV)	\$570.4 M	26%	\$716.0 M

The New Frontiers cost cap is \$650M (FY2009 \$) excluding the launch vehicle. The use of a medium range launch vehicle (e.g. Atlas V 541) increases the cap \$40M, to a total PI-managed mission cost of \$690M. This pre-Phase A design has a total PI-managed mission cost of \$716M (\$26M above cap).

### Acknowledgements

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